



(Following Paper ID and Roll No. to be filled in your Answer Book)

**PAPER ID : 0301****Roll No.**

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**B.Tech.****(SEM. VII) ODD SEMESTER THEORY EXAMINATION****2010-11****TELEMETRY AND DATA TRANSMISSION***Time : 3 Hours**Total Marks : 100***Note :** (1) Attempt **all** questions.

(2) All questions carry equal marks.

(3) Be precise in your answers.

1. Attempt any **four** part : **(4×5=20)**
  - (a) Write down the principle of PLL and give the application.
  - (b) Discuss the data transmission over telephone lines.
  - (c) Define FSK, PSK and draw the block diagram of QPSK receiver.
  - (d) Explain with block diagram Dual slope integrator type A/D converter.
  - (e) State and prove Shannon sampling theorem.
  - (f) Describe serial interface with RS-232C.
2. Attempt any **two** parts of the following : **(2×10=10)**
  - (a) Explain tone digital command system and data command system with suitable examples of industrial processes.
  - (b) What types of display systems are used in Telemetry application ? Explain them with few examples.
  - (c) What is bit acquisition and bit slip ? What is the use of bit synchronizer ?

3. Attempt any **two** parts : (2×10=20)
- (a) Write in brief :
- (i) Frame Structure
  - (ii) Frame Timing
  - (iii) Traffic Burst Structure.
- (b) What is PLC ? How it is useful in factory automation ? Explain.
- (c) Explain the principle of Time division multiplexing.
4. Attempt any **two** parts : (2×10=20)
- (a) Describe cross talk and give some possibilities for reducing its effects.
- (b) Draw the block diagram of tone raised command system and explain it.
- (c) (i) Explain TDM and  $T_1$  frame channel synchronization in TDM.
- (ii) Write a short note on Reliability of tele control installations.
5. Attempt any **four** parts : (4×5=20)
- (i) Explain aliases.
  - (ii) Explain PCM with the help of suitable diagrams.
  - (iii) Explain the principle FDM.
  - (iv) Explain the purpose of Signal conversion with the help of examples.
  - (v) What is sampling theorem ?
  - (vi) What is Telemetry, Tracking & Command System ?

